A Probabilistic Approach to the Interpretation of Spoken Utterances

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Abstract. In this paper we describe *Scusi?*, the speech interpretation component of a spoken dialogue module designed for an autonomous robotic agent. *Scusi?* postulates and maintains multiple interpretations of the spoken discourse, and employs a probabilistic formalism to assess and rank hypotheses regarding the meaning of spoken utterances. These constituents in combination enable *Scusi?* to cope gracefully with ambiguity and speech recognition errors. The results of our evaluation are encouraging, yielding good interpretation performance for utterances of different types and lengths.

1 Introduction

The *DORIS* project aims to develop a spoken dialogue module for an autonomous robotic agent, which supports the generation of responses that require physical as well as dialogue actions. In this paper, we describe *Scusi?*, *DORIS*'s language interpretation component, focusing on the techniques used to postulate and assess hypotheses regarding the meaning of a spoken utterance.

Minimally, a language interpretation component must be able to postulate promising interpretations, and decide whether there is a clear winner or several likely candidates to be passed to the dialogue system. These capabilities provide the basis for additional desiderata, viz recovering from erroneous interpretations, and adjusting interpretations dynamically as new information becomes available. The dialogue system in turn must determine an appropriate action. For example, consider the request "get me the blue mug". If there is an aqua mug, an indigo mug and a light blue mug in view, the robot could do one of the following: (1) pick the 'bluest' mug among these candidates, (2) select one of these mugs at random, (3) ask a clarification question, or (4) look for a mug that better fits the request. The chosen action depends on the certainty associated with the options returned by the language interpretation module, and the decision procedures applied by the dialogue system.

In order to support the above capabilities, a discourse interpretation system should (1) maintain multiple interpretations, and (2) apply a ranking process to assess the relative merit of each interpretation. *Scusi?* does this, employing a probabilistic mechanism for the ranking component. Its interpretation process comprises three stages: speech recognition, parsing and semantic interpretation. Each stage produces multiple candidate options, which are ranked according to their probability of matching the speaker's

intention (Section 3). This probabilistic framework, together with the maintenance of multiple interpretations at each stage of the process, enable *Scusi?* to cope with ambiguity and speech recognition errors (Section 5). In addition, these constituents support the re-ranking of interpretations as new information becomes available, and hence the recovery from erroneous interpretations; and they enable *Scusi?* to abstract features of the interpretations which support the generation of appropriate dialogue or physical actions. Examples of these features are: number of highly ranked interpretations, the difference in their probability, and the similarity between them.

This paper is organized as follows. Section 2 outlines the interpretation process. The estimation of the probability of an interpretation appears in Section 3, and the semantic interpretation procedure in Section 4. Section 5 details our evaluation. Related research and concluding remarks are given in Sections 6 and 7 respectively.

2 Multi-stage Processing

Scusi? processes spoken input in three stages: speech recognition, parsing and semantic interpretation (Figure 1(a)). Our probabilistic approach resembles that of Miller *et al.* [1]. However, they considered textual input, and used semantic grammars tailored to a slot-filling application. In contrast, our grammars are syntactic, and we incorporate domain-related information only in the final stage of the interpretation process, which yields Conceptual Graphs [2] — a more general structure than frames.

In the first stage of our interpretation process, Scusi? runs Automatic Speech Recognition (ASR) software (Microsoft Speech SDK 5.1) to generate candidate texts from a speech signal. Each text is assigned a score that reflects the probability of the words given the speech wave. The second stage applies Charniak's probabilistic parser (ftp://ftp.cs.brown.edu/pub/nlparser/) to generate parse trees from the texts. The parser generates up to N = 50 parse trees for each text, associating each parse tree with a probability. During semantic interpretation, parse trees are successively mapped into two representations based on Conceptual Graphs: first $Uninstantiated\ Concept\ Graphs\ (UCGs)$, and then $Instantiated\ Concept\ Graphs\ (ICGs)$. UCGs are obtained from parse trees deterministically — one parse tree generates one UCG (but a UCG can have more than one parent parse tree).

A UCG represents syntactic information, where the concepts correspond to the words in the parent parse tree, and the relations between the concepts are directly derived from syntactic information in the parse tree and prepositions. Each UCG can generate many ICGs. This is done by nominating different instantiated concepts (relations) from *DORIS*'s knowledge base as potential realizations for each concept (relation) in a UCG (Section 4). Instantiated concepts are objects or actions in the domain, and instantiated relations are similar to semantic role labels [3]. Figure 1(b) illustrates the generation of one ICG for the request "leave the blue mug on the table". The noun "mug" in the parse tree is mapped to the concept mug in the UCG, which in turn is mapped to the instantiated concept mug03 in the ICG. The preposition 'on' in the parse tree is mapped to the relation *on* in the UCG, and then to the relation *Destination* in the ICG. Noun modifiers, such as colour and size, are treated as features to be matched to those of instantiated objects in the knowledge base. For instance, the colour BLUE is

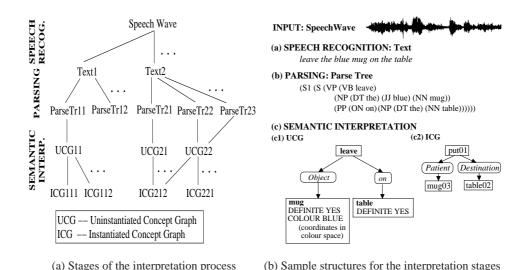


Fig. 1. Scusi?'s spoken language interpretation process

represented as a set of colour coordinates, which are then matched against the colour coordinates of stored objects [4].

The consideration of all possible options at each stage of the interpretation process is computationally intractable. *Scusi?* uses two computational devices to generate interpretations in real time: (1) an *anytime* algorithm [5], and (2) a processing threshold.

The anytime algorithm ensures that the system can return a list of ranked interpretations at any point after generating an interpretation component (text, parse tree, UCG or ICG). In each stage of the interpretation process, the algorithm applies a selectionexpansion cycle to add an element to a search graph (Figure 1(a)) as follows. First, it selects an option for consideration (speech wave, textual ASR output, parse tree or UCG), and expands this option to the next level of interpretation. When an option is expanded, a single candidate is returned for this next level, but additional options reside in a buffer, which is created the first time the option is expanded. For example, when we expand a particular text, the parser returns the next most probable parse tree (but the first time this text is expanded, a buffer with at most N parse trees is created). Similarly, when we expand a UCG, the ICG-generation module returns the next most probable ICG, but the first time the UCG is expanded, a buffer of at most k_{max} ICGs is created (Section 4). Buffers are used, rather than piecemeal generation of alternatives, due to two reasons: (1) the ASR and parser return all the options at once; and (2) owing to the complex interactions between the components of ICGs, ICGs are not generated in descending order of probability (i.e., the best ICGs are often generated later on). By maintaining an ICG buffer for each UCG, higher-probability ICGs that are generated later can be slotted into the buffer (and considered by the selection-expansion process) in the order that reflects their probability. The selection-expansion process is repeated until one of the following happens: all options are fully expanded, a time limit is reached, or a specific number of iterations is performed. At any point after completing an expansion, the anytime algorithm can return a list of ranked interpretations with their parent sub-interpretations (text, parse tree(s) and UCG(s)).

The **thresholding** approach is based on the observation that the probabilities of the texts returned by the ASR drop quite dramatically after the first few texts, as do the probabilities of the parse trees. We take advantage of this observation to prevent the consideration of unpromising alternatives as follows. When the probability of the next child of a parent node n drops below a threshold Thr relative to the probability of the most probable child of n, no additional children of n are considered. For example, for Thr = 50%, if the probability of the next parse tree for text T_i is less than half of the probability of the first (best) parse tree generated for T_i , no more parse trees are considered for T_i .

3 Probability of an Interpretation

Scusi? ranks candidate ICGs according to their probability of being the intended meaning of a spoken utterance. The principles of this calculation were set out in [6]. Here we refine this process, focusing on the calculation of the probability of ICGs.

Given a speech signal W and a context \mathcal{C} , the probability of an ICG I is represented as follows.

$$\Pr(I|W,C) \propto \sum_{\Lambda} \Pr(I|U,C) \cdot \Pr(U|P) \cdot \Pr(P|T) \cdot \Pr(T|W)$$
 (1)

where the UCG, the parse tree and the textual interpretations are denoted by U,P and T respectively. The summation is taken over all possible paths $\Lambda = \{P,U\}$ from the parse tree to the ICG, because a UCG and an ICG can have more than one parent. The ASR and the parser return an estimate of $\Pr(T|W)$ and $\Pr(P|T)$ respectively. In addition, $\Pr(U|P) = 1$, since the process of generating a UCG from a parse tree is deterministic. Hence, we still have to estimate $\Pr(I|U,\mathcal{C})$.

Consider an ICG I containing concepts $c^{ICG} \in \Omega_c$ and relations $r^{ICG} \in \Omega_r$ (Ω_c and Ω_r are the concepts and relations in the domain knowledge respectively). The parent UCG (denoted by U) comprises concepts $c^{UCG} \in \Gamma_c$ and relations $r^{UCG} \in \Gamma_r$ (Γ_c and Γ_r are the concepts and relations from which UCGs are built). The probability of I given U and context $\mathcal C$ can be stated as follows.

$$\begin{split} \Pr(I|U,\mathcal{C}) &= \prod_{\substack{c^{\mathit{ICG}} \in \Omega_c \\ r^{\mathit{ICG}} \in \Omega_r}} \Pr\left(c^{\mathit{ICG}}, r^{\mathit{ICG}} | c^{\mathit{UCG}}, r^{\mathit{UCG}}, \Omega_c^-, \Omega_r^-, \mathcal{C}\right) \\ &= \prod_{\substack{c^{\mathit{ICG}} \in \Omega_c \\ r^{\mathit{ICG}} \in \Omega_c \\ r^{\mathit{ICG}} \in \Omega_r}} \left\{ \Pr\left(r^{\mathit{ICG}} | c^{\mathit{ICG}}, c^{\mathit{UCG}}, r^{\mathit{UCG}}, \Omega_c^-, \Omega_r^-, \mathcal{C}\right) \times \Pr\left(c^{\mathit{ICG}} | c^{\mathit{UCG}}, r^{\mathit{UCG}}, \Omega_c^-, \Omega_r^-, \mathcal{C}\right) \right\} \end{split}$$

where $e^{{\scriptscriptstyle UCG}}$ and $r^{{\scriptscriptstyle UCG}}$ denote the UCG concept and relation corresponding to the ICG concept $e^{{\scriptscriptstyle ICG}}$ and relation $r^{{\scriptscriptstyle ICG}}$ respectively; and Ω_c^- and Ω_r^- denote the sets Ω_c and Ω_r without the concept $e^{{\scriptscriptstyle ICG}}$ and relation $r^{{\scriptscriptstyle ICG}}$ respectively.

It is difficult to estimate Equation 2, as each concept and relation in an ICG depends on the other ICG concepts and relations. We therefore make the following simplifying assumptions.

- The probability of an ICG relation r^{ICG} depends only on the corresponding UCG relation, the parent ICG concept of r^{ICG} , and the context.
- The probability of an ICG concept c^{ICG} depends only on the corresponding UCG concept, the parent ICG relation and grandparent ICG concept of c^{ICG} , and the context (e.g., the parent relation of mug03 in the ICG in Figure 1(b) is *Patient*, and its grandparent concept is put01).

These assumptions are justified by the information in the knowledge base, which stores the location and ownership of many objects, and by the available linguistic information regarding concepts and relations (e.g., the action fetch01 has a mandatory *Patient* relation, but an optional *Beneficiary*, and any mug is a suitable *Patient* for most actions). Now, say we have the request "get the mug from the table", and one of the candidate ICGs has the fragment [mug03 \rightarrow *Location* \rightarrow table01] (*Location* is the parent of table01, and mug03 is its grandparent). If mug03 is indeed on table01, the probability of this ICG increases, otherwise it decreases. In the absence of this information, we back off to bigram probabilities (e.g., whether table01 is a possible *Location*). These assumptions yield

$$\Pr(I|U,\mathcal{C}) \approx \prod_{\substack{c^{ICG} \in \Omega_c \\ r^{ICG} \in \Omega_r}} \left\{ \Pr(r^{ICG}|r^{UCG}, c_p^{ICG}, \mathcal{C}) \times \Pr(c^{ICG}|c^{UCG}, r_p^{ICG}, c_{gp}^{ICG}, \mathcal{C}) \right\}$$
(3)

where the parent concept of relation $r^{{\scriptscriptstyle ICG}} \in \varOmega_r$ is $c_p^{{\scriptscriptstyle ICG}} \in \varOmega_c$, and the grandparent concept and parent relation of concept $c^{{\scriptscriptstyle ICG}} \in \varOmega_c$ are $c_{gp}^{{\scriptscriptstyle ICG}} \in \varOmega_c$ and $r_p^{{\scriptscriptstyle ICG}} \in \varOmega_r$ respectively.

After applying Bayes rule, and making additional simplifying assumptions about conditional dependencies, we obtain

$$\Pr(I|U,\mathcal{C}) \approx \prod_{\substack{c^{ICG} \in \Omega_c \\ r^{ICG} \in \mathcal{O}}} \left\{ \underbrace{\frac{\Pr(r^{UCG}|r^{ICG})}{\Pr(c^{UCG}|c^{ICG})}}_{\text{segment 1}} \underbrace{\frac{\Pr(r^{ICG}|c_p^{ICG})}{\Pr(c^{ICG}|r_p^{ICG}, c_{gp}^{ICG})}}_{\text{segment 2}} \underbrace{\frac{\Pr(c^{ICG}|\mathcal{C}) \times}{\Pr(c^{ICG}|\mathcal{C})}}_{\text{segment 3}} \right\}$$
(4)

The first segment in Equation 4 represents the probability that a user who intended $r^{{\scriptscriptstyle ICG}}$ and $c^{{\scriptscriptstyle ICG}}$ respectively; the second segment represents the probabilities of relations and concepts in the ICG in light of their parent and grandparent nodes; and the third segment represents the prior probabilities of the concepts in the ICG (judicious conditionalization obviates the calculation of prior probabilities of relations in the ICG). Ideally, all these probabilities should be estimated from data, but this would require the development of a large database of UCGs and ICGs corresponding to different utterances. Such a database is currently not available. Hence, Scusi? estimates the necessary probabilities using functions which give a probabilistic interpretation to the closeness between requested features and features of the candidate concepts and relations. These functions are described in detail in [7,4]. Here we outline our approach.

- The probabilities in the first segment of Equation 4 are estimated on the basis of the goodness of the match between candidate instantiated concepts (relations) in the ICG and concepts (relations) mentioned in the UCG [4]. For relations, this probability depends on the lexical match between a stated relation and an instantiated

- relation. For concepts we also take into account the left modifiers of the head noun at present we consider colour and size. For example, if the user said "blue mug", then a light blue cup will yield a lower probability than a royal blue mug.
- The probabilities in the second segment are estimated based on how well children nodes match the expectations of their parent (and grandparent) nodes in the ICG [7]. For example, the probability of the ICG bigram [go02 → Destination] depends on whether Destination is a compulsory complement of go02 (high probability) or optional (lower probability); the probability of the trigram [cup05 → Owned-by → Susan01] is 1 if Susan01 owns cup05, and 0.5 if ownership is unknown. At present, grandparent concepts are considered only for location and ownership of objects, which may be determined from the system's knowledge base. In other cases or if the information is unknown, we back-off to the parent relation of a concept, e.g., the probability of kitchen being a Location.
- The prior probability of an instantiated concept depends on the context. At present, the context includes only domain knowledge, i.e., all instantiated concepts have the same prior, hence it does not affect the performance of the system. However, visual and dialogue context will come into play when *Scusi?* interacts with the robot's vision system and *DORIS*'s dialogue module. To support these interactions, in the future, we propose to estimate the prior probabilities of concepts by combining salience scores obtained from dialogue history [8] with visual salience [9].

4 Generating ICGs

The process of generating ICGs from a UCG and estimating their probability is carried out by Algorithm 1, which refines the procedure presented in [6]. This algorithm generates a buffer containing up to k_{max} (= 400) ICGs ranked in descending order of probability the first time a UCG is expanded (the size of the buffer was empirically determined). Every time a new ICG is requested for that UCG, the next ranked ICG is returned. The algorithm has two main stages: concept and relation postulation (Steps 2–10), and ICG construction (Steps 11–16).

4.1 Postulating concepts and relations

In this stage, the algorithm proposes instantiated concepts (relations) from the knowledge base for each UCG concept (relation), and sorts each candidate list of instantiated concepts (relations) in descending order of probability.

In **Step 5**, for each concept $c^{\textit{UCG}}$ in the UCG, the algorithm estimates the probability that each instantiated concept in the knowledge base matches $c^{\textit{UCG}}$. The same is done for relations. The probability of this match, which corresponds to the first segment in Equation 4, is estimated by means of comparison functions [4]. The probability of a match between an instantiated relation and a UCG relation depends only on the goodness of the lexical match between these relations. In contrast, the probability of a concept match also depends on the match between intrinsic features mentioned in the UCG, such as colour and size, and the actual values of these features for a candidate instantiated concept. For instance, given the UCG concept cup, the instantiated concepts $\textit{mug01}, \ldots$,

Algorithm 1 Generate candidate ICGs for a UCG

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Require: UCG U comprising concepts c^{UCG} and relations r^{UCG}, context C
1: Initialize buffer \mathcal{I}_U of size k_{\max} (=400)
 2: for all concepts c^{UCG} (relations r^{UCG}) in U do
3:
       Initialize a list of candidate concepts L_{c^u} \leftarrow \emptyset (list of relations L_{r^u} \leftarrow \emptyset)
       for all instantiated concepts \mathbf{c}^{I} (instantiated relations \mathbf{r}^{I}) do
4:
          Compare c^{^{UCG}} with \mathbf{c^I} (r^{^{UCG}} with \mathbf{r^I}), yielding a probability for the match (segment 1 in
5:
          Equation 4)
          Calculate the prior probability of c^I according to the context C (segment 3 in Equa-
6:
          tion 4)
7:
          Multiply the probabilities obtained in Steps 5 and 6
8:
          Insert \mathbf{c}^I in the list L_{c^u} (\mathbf{r}^I into L_{r^u}) in descending order of probability
       end for
10: end for
{ Construct ICGs }
11: for j = 1 to k_{max} do
       Generate the "next best" ICG I_i by going down each list L_{c_u} and L_{r_u} in turn
12:
13:
       Perform internal consistency checks to calculate the probabilities of the bigrams and tri-
       grams in ICG I_i (segment 2 in Equation 4)
14:
       Estimate Pr(I_j|U,C) by multiplying the probabilities obtained in Step 7 with the proba-
       bilities obtained in Step 13
15:
       Insert I_i into buffer \mathcal{I}_U in descending order of probability
16: end for
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mug05 and cup01,..., cup04 have a good lexical match with the UCG concept. If the UCG concept had been *blue cup*, then the colour coordinates of the mugs and cups in the knowledge base would be matched against the coordinates for the term 'blue'.

Upon completion of Step 5, we prune ICG candidates that do not have a good match with the concept (relation) in the UCG. For example, the UCG concept *chair* could refer to an armchair, a stool, a pouf, etc. Hence, all the armchairs, stools, poufs, etc in the knowledge base are retained for further processing, while lamps, tables, cups, etc are discarded. Similarly, red cups are discarded if a blue mug is requested, and there are blue mugs in the knowledge base.

The prior probability of the retained candidate concepts (third segment in Equation 4) is estimated in **Step 6**. In **Step 7**, this probability is multiplied by the probability calculated in Step 5.

This stage of the algorithm yields a list of candidate instantiated concepts L_{c^u} for each UCG concept c^{vco} , and a list of candidate instantiated relations L_{r^u} for each UCG relation r^{vco} . These lists are sorted in descending order of probability. For example, Table 1 shows the sorted lists of concepts and relations postulated for the request in Figure 1(b) "leave the blue mug on the table": there are four objects that are a good match for the concept blue mug, three candidate tables, three candidate actions for leave (leave the room (leave01), put in a specific place (put01), and put down (put02)), two relations for on, and one for object.

Table 1. Concepts and relations used to build ICGs for the utterance "leave the blue mug on the table"

leave	blue mug	table	on	object
leave01	mug02	table01	Destination	Patient
put01	cup01	table02	Location	
put02	mug03	table03		
	cup02			

4.2 Constructing ICGs

In this stage, the algorithm uses the list of instantiated concepts (relations) built for each concept (relation) in a UCG to construct candidate ICGs for this UCG, and sorts these ICGs in descending order of probability. First, Step 12 applies an enumerative process to generate different combinations of concepts and relations from the list L_{c_u} (L_{r_u}) maintained for each UCG concept (relation). This is done by iteratively selecting one candidate concept (relation) from each list. For instance, the concepts and relations in Table 1 are combined as follows to build candidate ICGs. First, the top line $\{1eave01, mug02, \ldots\}$, which has the highest probability, is used. The next four combinations are generated by replacing one element from this line at a time, i.e., 1eave01 is replaced with put01, yielding $\{put01, mug02, \ldots\}$; then mug02 is replaced with cup01, yielding $\{1eave01, cup01, \ldots\}$; and so on.

The probabilities of the bigrams and trigrams in each ICG (second segment in Equation 4) are then estimated in **Step 13**. These probabilities reflect the extent to which the relationships between neighbouring nodes in an ICG match the known reality. As mentioned in Section 3, for relations this calculation is done based on the type of relations admitted by each concept (e.g., compulsory, optional or absent), and for concepts the calculation reflects the current state of the world. For example, if we request "the mug on the table" and according to the knowledge base, mug03 is on table02, the probability of an ICG that contains [mug03 \rightarrow Location \rightarrow table02] is increased, whereas if cup01 is not on a table, the probability of an ICG containing cup01 is decreased. In **Step 14**, these 'structural' probabilities are combined with the probability calculated in Step 7 (candidate postulation stage) to obtain the final probability of an ICG produced for a given UCG. This ICG is inserted in the buffer for that UCG in descending order of the ICG's probability.

5 Evaluation

Our evaluation test set comprised 100 utterances: 43 declarative (e.g., "the book is on the desk", "in the kitchen", "the red mug") and 57 imperative (e.g., "open the door"). These utterances were based on interactions between users and a "robot" (enacted by

¹ We acknowledge the modest size of this test set compared to that of some publicly available corpora, e.g., ATIS and GeoQuery. However, we must generate our own test set since our task differs significantly from the slot-filling tasks where these large corpora are used. This is due to the domain itself and the open-ended nature of the utterances.

one of the authors) in a virtual home scenario; they were recorded by one of the authors, as the ASR software is speaker dependent, and at present we do not handle features of spontaneous speech. The utterances (which were not used during system development) were chosen to test *Scusi?*'s ability to identify target objects (the intended book, mug, table, etc), and its ability to handle phenomena such as synonyms (e.g., "wash" and "clean") and homonyms (e.g., "leave the mug on the table" versus "leave the room"). The average utterance length was 8.5 words, with a maximum length of 12 words.

Scusi? was set to generate at most 300 sub-interpretations in total (including texts, parse trees, UCGs and ICGs) for each utterance in the test set; on average, it took 6 seconds to go from parse trees to ICGs. An interpretation was deemed successful if it correctly represented the speaker's intention within the limitations of Scusi?'s knowledge base, which comprises 135 items (24 relations and 111 concepts, which consist of abstract concepts and concrete objects normally found in a house). This intention was represented by one or more Gold ICGs that were manually constructed by one of the authors. Multiple Gold ICGs were allowed if there were several objects in the knowledge base that matched a requested object, e.g., "get a mug".

Ideally, we would like to evaluate separately the impact of our probabilistic framework and that of maintaining multiple interpretations. However, the design of an alternative, baseline hypothesis-ranking framework is outside the scope of this project. We therefore designed our experiments to measure (1) *Scusi?*'s overall interpretation performance, (2) the impact of maintaining multiple interpretations on performance, and (3) the impact of different thresholds (Section 2). Thus, tests were conducted under the following settings.

- BASELINE a beam search was executed, where only the best ASR result was parsed, and only the best parse tree yielded a UCG. We then selected the top ICG among those in the buffer for the UCG (Section 4). Note that the selection of the top-ranked item for each of these stages is still done on the basis of its probability. Hence, our baseline enables us to isolate only the impact of maintaining multiple interpretations.
- Threshold No Threshold, and thresholds of 10%, 20%, 50%, 80% and 90%. For instance, given a 10% threshold, *Scusi?* stops expanding a text T such that $Pr(\text{current parse tree for } T) < 0.1 \times Pr(\text{highest-probability parse tree for } T)$.

Table 2 summarizes our results, which were obtained with an ASR that had a 20% error rate (the correct text was top ranked by the ASR in 80% of the cases). Column 1 displays the test condition (baseline and threshold value). Columns 2-3 show how many utterances had Gold ICGs whose probability was among the top 1 or top 3, e.g., the 20% threshold yielded 70 Gold ICGs with the highest probability (top 1), and 83 within the top 3 probabilities. The average *adjusted rank* and *rank* of the Gold ICG appear in Column 4. The rank of an ICG I is its position in a list sorted in descending order of probability (starting from position 0), such that all equiprobable ICGs are deemed to have the same position (recall that the baseline returns a single ICG, whose rank is therefore 0). The adjusted rank of an ICG I is the mean of the positions of all ICGs that have the same probability as I. For example, if we have 3 top-ranked equiprobable ICGs, each has a rank of 0, but an adjusted rank of $\frac{0+2}{3}$. Column 5 shows how many utterances didn't yield a Gold ICG, and Column 6 indicates the average number of

Table 2. *Scusi?*'s interpretation performance

	# Gold ICGs with prob in		Average	Not	Avg # of ICGs to Gold
	top 1	top 3	adj rank (rank)	found	ICG (avg # of iters)
BASELINE	53	53	0 (0)	47	0 (4)
No Thrsh	69	82	3.85 (1.15)	7	9 (38)
10%	67	81	2.63 (0.91)	8	8 (37)
20%	70	83	2.47 (0.87)	7	8 (39)
50%	70	84	2.37 (0.81)	7	8 (37)
80%	70	85	2.31 (0.80)	7	8 (37)
90%	70	85	2.31 (0.78)	7	8 (37)
Total	100	100			

ICGs created and iterations done until the Gold ICG was found (from a total of 300 iterations).

As seen in Table 2, the baseline yielded significantly fewer top-ranked Gold ICGs than our anytime algorithm (p < 0.05). The 20% ASR error was substantially exacerbated by the baseline approach, which failed to return Gold ICG(s) in 27 of the 80 cases where it was presented with the correct text. In contrast, *Scusi?* performed significantly better, failing to produce top-ranked Gold ICG(s) in only 10 of those cases. Further, for the top-3 ranking, *Scusi?* overcame the ASR error (i.e., its error rate is less than 20%). These results confirm the need to maintain multiple interpretations in combination with a probabilistic hypothesis assessment.

Interestingly, the threshold did not affect the number of top-ranked Gold ICGs and not found ICGs, and the number of iterations to Gold. However, the average rank of the Gold ICGs decreases (improves) as the threshold increases, which is consistent with the slight improvement in the number of top-3 ICGs. We also performed additional experiments that examined the effect of using a different threshold for each level of interpretation. However, the new scheme did not yield any improvement over a single system-wide threshold.

6 Related Research

This research builds on the work described in [5,6]. The contributions of this paper pertain to (1) the anytime algorithm and processing threshold (Section 2); (2) the probabilistic calculation of the factors of $\Pr(I|U,\mathcal{C})$, instead of using heuristics (Section 3); and (3) the modifications of the UCG representation to cater for intrinsic features of a node (Section 2), and ensuing changes in the algorithm for generating ICGs (Section 4). These modifications led to an improved performance of the system, which was evaluated on a larger corpus than that used in [6].

² Sample paired t-tests were used for all statistical tests.

³ Clearly, it is not fair to compare *Scusi?*'s top-3 rank with the baseline's top-1 rank. However, the top-3 rank supports the generation of clarification questions for ICGs with similar probabilities — an option that is not available if only the top-ranked interpretation is returned.

Many researchers have investigated numerical approaches to the interpretation of spoken utterances in dialogue systems, e.g., [10–13]. Pfleger et al. [10] and Hüwel and Wrede [11] employ modality fusion to combine hypotheses from different analyzers (linguistic, visual and gesture), and apply a scoring mechanism to rank the resultant hypotheses. In contrast, He and Young [12] and Gorniak and Roy [13] apply a probabilistic approach to spoken language interpretation, using Hidden Markov Models for the ASR stage. Additionally, as mentioned above, Scusi?'s probabilistic formalism resembles in style that employed by Miller et al. for discourse interpretation in a textbased system [1]. However, all these systems employ semantic grammars, while Scusi? employs a three-stage interpretation process, which uses generic, syntactic tools, and incorporates semantic- and domain-related information only in the final stage of the interpretation process. Knight et al. [14] compare the performance of a dialogue system based on a semantic grammar to that of a system based on a statistical language model and a robust phrase-spotting grammar. The latter performs better for relatively unconstrained utterances by users unfamiliar with the system. The probabilistic approach and intended users of our system are in line with this finding.

From the view point of application domain, robot-mounted dialogue systems were also studied in [15, 16, 11]. Matsui *et al.* [15], like Gorniak and Roy [13], use contextual information to constrain the alternatives returned by the ASR early in the interpretation process. This allows their system to process expected utterances efficiently, but makes it difficult to interpret unexpected utterances. In contrast, *Scusi?* incorporates contextual information in the final stage of the interpretation process. Unlike *Scusi?* is probabilistic reasoning formalism, Bos *et al.* [16] use a logic-based language interpretation framework to understand instructions and descriptions, and employ formal proofs for conflict resolution. Consequently, alternatives are not considered when an utterance is ambiguous or the preferred option proves undesirable. This is also the case for Hüwel and Wrede's [11] system, which considers only a single alternative as a result of each stage of the interpretation process.

7 Conclusion and Future Work

We have described *Scusi?*, a spoken language interpretation system that maintains multiple options at each stage of the interpretation process, and ranks interpretations based on estimates of their posterior probability. In particular, we presented the algorithm used by *Scusi?* to postulate hypotheses regarding the meaning of a spoken utterance, and detailed the estimation of the probabilities of these hypotheses.

Our empirical evaluation shows that *Scusi?* performs well for declarative and imperative utterances of varying length, with the Gold ICG(s) receiving one of the top three probabilities for most test utterances. Our results also show that using a threshold has a small impact on *Scusi?*'s performance (by slightly improving the number of ICGs ranked top-3, and hence the average rank of the Gold ICGs). In the near future, we will further investigate the impact of thresholds on performance speed and accuracy. An additional avenue of investigation pertains to the consideration of different weightings for combining the scores obtained from the three interpretation stages.

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